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THEORETICAL NOTE

When Working Memory May Be Just Working, Not Memory

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The *N*-back task is often considered to be a canonical example of a task that relies on working memory (WM), requiring both maintenance of representations of previously presented stimuli and also processing of these representations. In particular, the set-size effect in this task (e.g., poorer performance on three-back than two-back judgments), as in others, is often interpreted as indicating that the task relies on retention and processing of information in a limited-capacity WM system. Here, we consider an alternative possibility: that retention in episodic memory (EM) rather than WM can account for both set-size and lure effects in the *N*-back task. Accordingly, performance in the *N*-back task may reflect engagement of the processing (“working”) function of WM but not necessarily limits in either that processing ability nor in retention (“memory”). To demonstrate this point, we constructed a neural network model that was augmented with an EM component, but lacked any capacity to retain information across trials in WM, and trained it to perform the *N*-back task. We show that this model can account for the set-size and lure effects obtained in an *N*-back study by M. J. Kane et al. (2007), and that it does so as a result of the well-understood effects of temporal distinctiveness on EM retrieval, and the processing of this information in WM. These findings help illuminate the ways in which WM may interact with EM in the service of cognitive function and add to a growing body of evidence that tasks commonly assumed to rely on WM may alternatively (or additionally) rely on EM.

Keywords: working memory, episodic memory, temporal context model, neural network models, *n*-back task

Immediate memory—that is, the ability to rapidly store and retrieve information after a short interval—is generally assumed to be served by two broadly distinguishable memory systems: working memory (WM) and episodic memory (EM).¹ WM is assumed to transiently maintain information in a capacity-limited fashion (Cowan, 2017; Oberauer et al., 2018). In contrast, EM stores information more durably, with few (if any) restrictions on capacity, in a latent form that can be retrieved later for use. While EM is usually not assumed to be subject to a storage capacity limitation

(Polyn et al., 2009; Tulving & Thomson, 1973), retrieval from EM is subject to interference from previously studied items, referred to as proactive interference (PI). Crucially, prior work has shown that PI during retrieval can account for forgetting in tasks with short retention intervals (e.g., Brown et al., 2007; Farrell, 2012; Oberauer et al., 2012; Unsworth et al., 2011). Here, we explore this idea in the context of the *N*-back task, by implementing a model of the task in which the retention of information across trials relies on EM rather than WM, and processing in WM uses a neural network to compare the information retrieved from EM with the information currently represented in the network. We use this model to demonstrate that effects in the *N*-back task often assumed to reflect processing and maintenance constraints associated with WM function—such as the set-size and lure effects—can also be produced by PI associated with the use of EM for retention. The model provides a mechanistic grounding for recent cognitive neuroscience work addressing contributions of EM to tasks that have traditionally been construed as relying on active maintenance in WM (e.g., Beukers et al., 2021; Foster et al., 2019; Hoskin et al., 2019) and also provides a point of contact with neural network models addressing the role of EM in higher cognitive function, both within cognitive science

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Simulation code can be accessed at <https://github.com/andrebeu/nback-paper>.

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¹ We specifically refrain from using the more familiar term “short-term memory” since EM, despite its capacity for rapid encoding, is usually referred to as a form of *long-term* memory due to the durability of its traces—an important factor that we discuss below.

(Webb et al., 2021) and machine learning (Graves et al., 2014; Ritter et al., 2018; Wayne et al., 2018).

WM, Retroactive Interference, and Set-Size Effects

WM is universally assumed to have a limited storage capacity (Oberauer et al., 2018; Sternberg, 1966), that is considered to be relatively strict (in the single digits; Cowan, 2017; Miller, 1956). This is often (but not always) attributed to the reliance on active maintenance as the mechanism of storage in WM, in which traces fail to be maintained because either they degrade with time, and/or are displaced by new ones.² The latter effect is often referred to as retroactive interference (A. Baddeley, 1992; Barnes & Underwood, 1959; Peterson & Peterson, 1959). In either case, as traces decay and/or newly activated ones interfere and displace them, older information is lost. Perhaps the empirical phenomenon that best exemplifies this is the set-size effect. The set-size effect, observed across a wide range of short-term memory and WM tasks (such as the classic Sternberg paradigm, Sternberg, 1966, and the *N*-back task Kirchner, 1958), refers to the observation that performance degrades as more items are required to be remembered—that is, the larger the size of the memory set, the more likely it is that information will be lost. One possible explanation of the set-size effect is that it arises from serial encoding into a limited-capacity WM system, whereby items in the set that were encoded earlier are subject to interference from those encoded later and/or decay due to the passage of time. However, the idea that set-size effects are a necessary sequela of WM engagement does not license the reverse inference, that the observation of set-size effects is a reliable indicator of WM engagement. As others have noted (e.g., Brown et al., 2007; Farrell, 2012; Oberauer et al., 2012; Unsworth et al., 2011), and we discuss below, there is a growing recognition that such effects can arise from the use of EM for storage and retrieval of recently presented information.

It is also worth noting that, in some tasks, set-size effects have also been attributed to demands on the *processing* capacity of WM which, in addition to its storage capacity, is also considered to be limited (A. D. Baddeley & Hitch, 1974). The *N*-back is a salient example of this (e.g., Rac-Lubashevsky & Kessler, 2016), as it has often been assumed to require the updating of the ordinal status of items in WM as each new stimulus is presented (i.e., what was the one-back stimulus must now be assigned as the two-back stimulus, and the two-back assigned as the three-back, etc.)—a processing requirement that would obviously increase with set-size. However, as discussed below, the use of EM can avert these processing demands, while still leading to substantial set-size effects.

EM, PI, and Temporal Context Effects

In contrast to the limited storage capacity of WM, EM is generally assumed to rely on a different mechanism of storage, in which traces are more durable (e.g., from hours to years) and are not subject to a restrictive capacity limit. However, such durable and (effectively) unrestricted storage carries with it its own limitations. Unlike WM, neither new traces nor time act to displace or degrade older memories in EM. However, as EM traces accumulate over time, the likelihood increases that a particular memory will be similar in some way to others. Because retrieval from EM is assumed to be content-based (Marr, 1971; Tulving & Thomson, 1973)—that is, items are

retrieved by presenting a cue and identifying items that are most similar to it—the challenge of identifying and retrieving a particular item increases as progressively more memories are stored. One of the well-known consequences of this problem of discriminability in EM is PI (Brown et al., 2007): the potential for older traces in EM to be confused with newer ones that are similar, and thus interfere with reliable retrieval of the latter. Thus, although the duration and capacity of storage in EM may be unlimited, its practical use is constrained by PI at retrieval.

One important elaboration of theories concerning EM is the incorporation of temporal context information into stored traces, that can be used for later retrieval (Howard & Kahana, 2002; Lohnas et al., 2015; Polyn et al., 2009). This has been used to explain not only how people can retrieve information from particular times in the past, but also—coupled with PI—the kinds of confusion errors they make when doing so. For example, it has been used widely to explain serial position and contiguity effects in free recall tasks (Kahana, 1996, 2020) and serial recall tasks (Brown et al., 2007), many of which share similarities with tasks used to probe WM. The effects of PI associated with temporal contiguity are especially relevant in tasks that require discrimination of items presented in close temporal proximity to one another—precisely the conditions of most WM tasks, and the *N*-back task in particular.

Thus, despite their different properties, both WM and EM suffer from forms of interference that can constrain memory performance. Whether it is the number of items that can be retained and/or processed in WM, or the number of items that can be reliably retrieved from EM, both systems exhibit a functional limitation that can manifest as set-size effects—a commonality that may confound the interpretation of such effects in behavioral data as evidence for the engagement of one memory system or the other.

Here, we use the *N*-back task to explore these possibilities, both because it has come to be one of the most widely used probes of WM engagement (e.g., Callicott et al., 1999; Cohen et al., 1994; Dobbs & Rule, 1989; Gevins & Cutillo, 1993; Jaeggi et al., 2010; M. Kane & Conway, 2023; M. J. Kane et al., 2007; Kirchner, 1958; Nikolin et al., 2021; Oberauer, 2005; Oberauer et al., 2018; Owen et al., 2005; Rac-Lubashevsky & Kessler, 2016; Ross, 1966), and because it is generally assumed to tax both the storage and processing capabilities of WM, as reflected in the profile of performance observed in the task. Specifically, we explore an account of performance in this task that has not been widely considered, in which: the storage and retrieval of previously presented information relies exclusively on EM; WM is used only to represent and process the most recently presented stimulus and memory retrieved from EM; and processing in WM involves simply comparing and making a decision based on that information (i.e., without the need to repeatedly update which item occurred in which previous position). To the extent that this account can explain the profile of performance in the *N*-back, including both set-size and lure effects, then it suggests that these need not reflect constraints on storage and/or processing in WM, but rather the effects of PI that can arise when stimuli with similar temporal encodings are retrieved in place of the correct ones—an effect that is consistent with temporal context models (TCMs) of EM and the large literature of empirical effects that are explained by these theories (Brown et al., 2007; Kahana, 2020).

² See, for example, Oberauer et al. (2012) and Oberauer (2019) for accounts of WM that challenge this focus on active maintenance.

We test the ability of this account to capture previously reported empirical effects in the *N*-back task, by implementing it in the form of a neural network model that is responsible for the representation and processing of information in WM; importantly, the model lacks any mechanism for the retention of previously presented stimuli in WM, but it is augmented with a simple form of EM that is used to encode, store, and retrieve previously presented stimuli. The latter corresponds closely to a form of “external memory” (i.e., a dictionary of previous events), that is gaining increasing use as a model of EM in cognitive science and neuroscience (e.g., Lu et al., 2022; Webb et al., 2021) as well as machine learning (e.g., Graves et al., 2014; Pritzel et al., 2017; Ritter et al., 2018; Wayne et al., 2018). We show that, even when there is *no* reliance on WM for storage, and the demands on processing are limited (i.e., simply making a decision based on a comparison of two sources of information), the model nevertheless exhibits empirically observed set-size and lure effects (described below), which emerge as a consequence of PI between traces in EM that incorporate similar temporal context representations.

The model consists of a feedforward neural network, coupled with a simplified implementation of a mechanism for context-based EM. The feedforward network implements the ability to compute on actively represented information (i.e., the “working” function of WM), but lacks any ability to retain that information after the relevant computations have been carried out and new information is presented to the network (i.e., it lacks the “memory” capabilities usually ascribed to WM). Rather, in the model, storage of information from one trial to the next—about the stimulus as well as temporal information that can be used to determine its serial position, both of which are required to perform the *N*-back task—relies on an EM module that encodes each stimulus and the temporal context in which it occurred. We first confirm that the encoding of temporal context information in EM traces causes memories encoded in close temporal proximity to interfere with one another, in a manner that can explain set-size effects observed in WM tasks. This initial result reaffirms prior work that has demonstrated the effects of temporal distinctiveness on memory retrieval (Brown et al., 2007), here using a formally simple mechanism for temporal encoding that is consistent in its properties with previous implementations (Manning et al., 2014). We show that this mechanism, coupled with a neural network mechanism trained to evaluate the temporal “distance” between stimuli, can reproduce empirically observed patterns of performance in the *N*-back task (Braver et al., 1997; M. J. Kane et al., 2007).

More specifically, in the *N*-back task (M. Kane & Conway, 2023; Kirchner, 1958), participants see a sequence of items presented one at a time and must indicate, for each item, whether that item matches the item that occurred *n* items ago in the sequence. This task requires the ability to retain previously seen stimuli as well as information about their serial position and to use that information to match the current stimulus with the relevant one retained in memory. We show that temporal context representations that change gradually with each stimulus presentation, and that are stored and can be retrieved from EM, can be used to estimate the serial position of an earlier stimulus and thereby perform the task; however, this also makes the process subject to PI, leading to set-size and lure effects.

In the sections that follow, we first provide an overview of the model, describing components that are relevant to all simulations. We then describe in detail how EM was implemented in the model, and discuss how similar temporal context representations can lead

to PI (following Brown et al., 2007). Next, we describe our implementation of the processing function of WM as a feedforward neural network, that is used to compare current information with the previous information stored in EM. Finally, we use the full model to simulate performance in the *N*-back task, showing how—despite the absence of a mechanism for retention of prior stimuli in WM and limited demands on WM for processing, the model is able to perform the task and, in doing so, exhibits set-size effects as well as other features of human performance in the task that can be attributed to PI as a result of the use of EM for storage and retrieval.

Method

Model Overview

The model consists of two components, an *EM component* and a *WM component*. The EM component is characterized by two operations: *encoding* and *retrieval*. Encoding involves storing the conjunction of features that correspond to a given stimulus. Following TCM implementations of EM (Estes, 1955; Kahana, 2020), an EM trace includes stimulus features as well as the temporal context in which the stimulus occurred. Importantly, traces stored in EM are enduring (i.e., they last the entire extent of a simulation) and latent (i.e., do not influence WM processing unless retrieved). Retrieval of these latent EM traces is carried out by a similarity-based sampling operation (Gillund & Shiffrin, 1984; Graves et al., 2014; Norman & O’Reilly, 2003; Shiffrin & Steyvers, 1997; Wayne et al., 2018; Webb et al., 2021). The stimulus is presented on each trial as perceptual input and an associated temporal context (i.e., the current one), which are used together as a retrieval cue that is compared to all traces stored in EM; the higher the similarity between the retrieval cue and a trace stored in EM, the higher the probability of that trace being retrieved.³

The WM component is implemented as a strictly feedforward neural network (i.e., without any recurrence), which implements the constraint that, in this model, WM can only represent and process information that is immediately presented to it, from the environment and/or from EM; that is, it is restricted to the “working” component of WM. Specifically, its role is to compare the current perceptual and temporal context information with memories retrieved from EM, and select a response based on whether the stimulus information matches, while the temporal context information differs by *n*.

Below, we show how—even though this model does not rely on WM for the retention of information across trials, and the processing demands on WM are limited (i.e., to a comparison operation but not any updating operations), while it has no constraints on the storage capacity of EM—errors can nevertheless arise due to PI that is the result of similarity in the temporal codes among traces in EM. In the following sections, we describe the implementation of each of these two model components in greater detail. We start, in Section EM Component, by describing the implementation of the EM component of the model. This includes a mechanism for generating temporal

³ Similarity-based retrieval can be thought of as a computational approximation to the neurobiological mechanism of retrieval from EM (e.g., hippocampal pattern completion; Marr, 1971; McClelland et al., 1995). Similarity-based retrieval is also playing an increasingly important role in machine learning models that address human-level cognitive function, both in the attention mechanisms of transformers (Altabaa et al., 2023; Vaswani et al., 2017), and as an augmentation to neural network models with a form of external memory (e.g., Graves et al., 2014; Pritzel et al., 2017; Ritter et al., 2018; Wayne et al., 2018; Webb et al., 2021).

context information, together with an analysis that directly examines its effects on serial position information encoded by context representations. Then, in Section WM Component, we describe the feedforward neural network architecture that is used to implement WM and makes use of information stored in EM to perform the N -back task.

EM Component

EM Encoding

For every stimulus presented to the model at test, a corresponding representation was formed and stored as an EM trace. Each EM trace was a concatenation of a one-hot stimulus vector and a continuous-valued context vector (described in Section Formulation of Context Representations). Because we assume EM has no practical capacity limitation, a new trace was appended to EM storage for each stimulus that was presented over the course of a simulation. Thus, for every trial, EM contained a list of all items previously presented to the model during that simulation. Memories were encoded in EM immediately *after* being processed by the neural network as the sensory input for the current trial. This was to prevent retrieval of the current stimulus from EM on the same trial in which it was also the sensory input.

Formulation of Context Representations

Implementation of EM in the model followed the approach taken in previous applications of TCM (Estes, 1955; Howard & Kahana, 2002; Lohnas et al., 2015; Mensink & Raaijmakers, 1988; Polyn et al., 2009), using context representations that were implemented in a neurally plausible form that not only changed noisily and gradually over time, but were also bounded in magnitude. To meet these criteria, we modeled context representations as an n -dimensional vector of scalar values between 0 and 1 that evolved gradually according to a random walk on an n -dimensional hypersphere. This context drift process was defined by the following equation:

$$C_t = F(\Phi_t^1, \Phi_t^2, \dots, \Phi_t^{n-1}) = F(\Phi_{t-1}^1 + N(\mu, \sigma), \Phi_{t-1}^2 + N(\mu, \sigma), \dots, \Phi_{t-1}^{n-1} + N(\mu, \sigma)). \quad (1)$$

At each timepoint, $n - 1$ polar coordinates Φ_{t-1} were updated by summing a Gaussian term $N(\mu, \sigma)$.⁴ That is, the context equation was defined as a Gaussian drift process on hypersphere of dimension n . We set the dimension of the hypersphere ($n = 25$) to be sufficiently large so as to minimize the likelihood that the vector would repeat (i.e., cycle among the same set of values). We set $\mu = 0.25$ and $\sigma = 0.075$ to best fit the behavioral data. Next, in Section Analysis of Context Representation, we provide an analysis of the evolution of this temporal context representation, showing how this can give rise to PI in EM, and consequently lead to set-size effects in tasks that involve sequential presentation of stimuli over trials.

Analysis of Context Representation

In this section, we present analyses showing that the contextual drift (Estes, 1955; Howard & Kahana, 2002; Lohnas et al., 2015; Mensink & Raaijmakers, 1988; Polyn et al., 2009) and temporal distinctiveness (Bjork & Whitten, 1974; Brown et al., 2007;

Glenberg et al., 1980) properties of our model can produce set-size effects. Then, in Section Results, we integrate this mechanism with the feedforward neural network described below and show that together these mechanisms can explain detailed patterns of behavioral performance, including set-size effects, observed for human performance in the N -back task.

Our account starts with the idea, taken from context-based models of memory, that items are tagged with a contextual representation that drifts noisily over time (Brown et al., 2007; Estes, 1955; Howard & Kahana, 2002; Lohnas et al., 2015; Mensink & Raaijmakers, 1988; Polyn et al., 2009), as described above. Contextual drift provides a basis for making temporal discriminations based on context representations. For example, consider the task of discerning the relative serial positions of two previously presented items (e.g., which item was presented two items vs. three items ago). If the goal is to select the more recent of the two items, one approach would be to compare the context tags associated with those items to the current context and choose the item with the smaller contextual distance to the current context—the principle of contextual drift implies that on average the contextual distance should be smaller for more recent items (Hintzman, 2002). However, because of accumulated noise in the contextual drift process, the variance associated with this contextual distance measure also increases as a function of the temporal distance. As a consequence of this increase in variance, the distributions of contextual distance scores associated with nearby serial positions will overlap more as a function of elapsed time relative to some reference (e.g., the present). Concretely, if we fix the time elapsed between studying the two items, the relative serial positions of which are being judged, but vary the temporal distance between these two items and the memory test (e.g., if the two items were studied in adjacent list positions, and we vary whether the two items were studied 1 min ago vs. 20 min ago), it will be more difficult to distinguish the relative serial positions of the items as they recede into the past due to increased variance in contextual distance. This effect reflects a form of parallax, that has been described in the literature by analogy to telephone poles receding into the distance: The further the telephone poles are in the distance, the harder it is to tell apart adjacent poles (Crowder, 1976).

Previously, Brown et al. (2007) argued that the diminution of temporal distinctiveness among items as function of their distance from a reference can lead to a corresponding degradation in the ability to recall more distant items because of increased competition (i.e., if the items are less distinguishable, it is more difficult to select out a specific item). Here, we hypothesized that this reduction in temporal distinctiveness for less recent items can provide a basis for the set-size effect in the N -back task. This effect manifests as an increase in errors and/or response times with greater n 's (Oberauer et al., 2018); for example, performance is worse on the three-back version of the task than the two-back version. As noted earlier, the set-size effect in the N -back task is often assumed to reflect a limitation in the maintenance and/or processing capabilities of WM, with three items subject to greater degradation or processing demands than two items. Here, we propose that this effect can also be produced by the increase in confusability between different context representations with increasing temporal distance, without any contribution was constraints on WM. For example, the three-

⁴ Note that to specify a hypersphere in n , only $n - 1$ coordinates are needed.

back task involves discriminating three-back targets from items two-back that are potential lures; and, similarly, the two-back task involves discriminating two-back targets from one-back lures. By the logic outlined above, the former (three-back) task will be more difficult because the target and lures, even if they are adjacent, occurred further back in time, so the associated contextual distances will be more variable and thus harder to discriminate (by analogy, it is harder to determine exactly which “telephone pole” is the one three-back); this effect is illustrated in Figure 1.

WM Component

Feedforward Neural Network Architecture

Processing in WM was implemented as a feedforward neural network. On each trial, the network was given information about the current task (two-back vs. three-back), the current stimulus presented to perception (letter on a computer screen), a representation of the temporal context of the current stimulus (i.e., distinct for each stimulus; see Section Formulation of Context Representations), and a memory trace retrieved from EM based on the current stimulus (explained below). The input layer consisted of five input pools: The first two pools represented the currently perceived stimulus (s_t ; represented as a one-hot vector) and its associated temporal context representation (c_t ; described below); the next two pools used the same coding scheme to represent the stimulus and context components of a memory trace (s_m, c_m , respectively), retrieved from EM (see Section EM Component); the final pool was a two-dimensional one-hot vector k that instructed the model about the task condition (e.g., two vs. three back in the *N*-back task). The current stimulus and context, together with the retrieved stimulus and context, were projected to the first hidden layer (h_1). The one-hot task instruction vector was also projected and summed into h_1 . Then, the resulting vector was projected to an additional hidden layer (h_2) that, in turn, projected to an output layer used to represent the response of the network to the current stimulus, indicating whether or not it judged that stimulus to match the n^{th} previously

presented stimulus. Processing in the feedforward network was defined by the following equations (see also Figure 2):

$$h_1 = f(s_t, c_t, s_m, c_m) + f(k) \quad h_2 = f(h_1) \quad \text{output} = s_m(h_2), \quad (2)$$

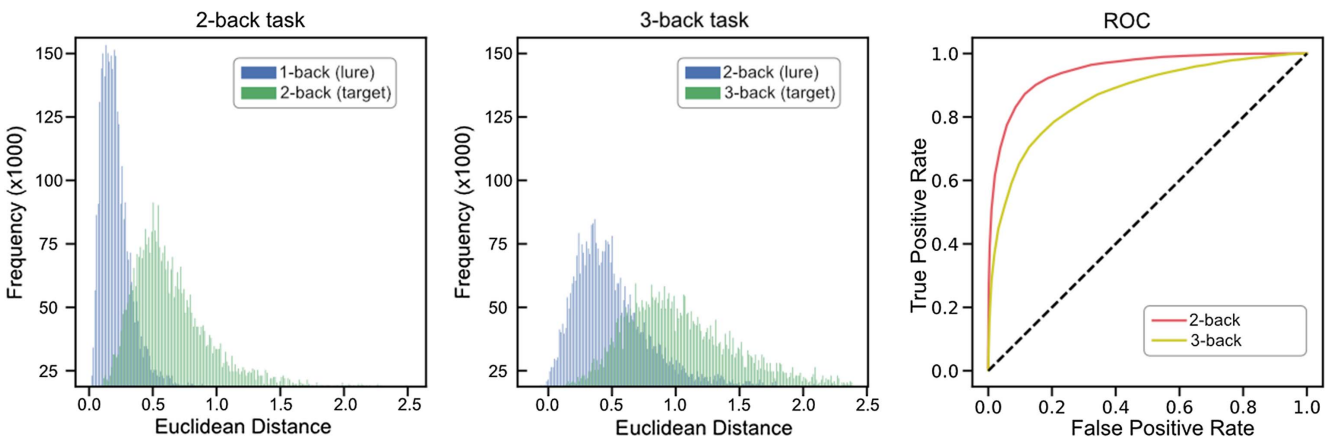
where s_t and s_m are 20-dimensional vectors representing stimuli, and c_m and c_t are 25-dimensional vectors representing context; $f(\cdot)$ is an 80-unit feedforward layer with rectified linear units (ReLU); $s_m(\cdot)$ is a softmax nonlinearity mapping from hidden units to output units; and output is a two unit layer with activation of the first unit representing the probability of a “yes” response, and activation of the second unit representing the probability of a “no” response.

The patterns of activity provided as input to the network, together with those over its hidden units (including the representations retrieved from EM), can be thought of as the information currently represented in WM, while computations carried out on these patterns of activity constitute the “working” function of WM. Note that none of the units in this network have persistence or integrator properties—whenever a new stimulus is presented and/or a retrieval is made from EM, they fully replace the previous corresponding patterns of activity. Nor are there any recurrent connections among units within or between layers. Thus, the network does not have the capacity to actively maintain any information in WM across stimulus presentations, nor do its prior states in any way influence its current computations. Rather, retention of information and any other effects of memories from prior trials are subserved exclusively by the EM component of the model, as described above.

Feedforward Neural Network Training

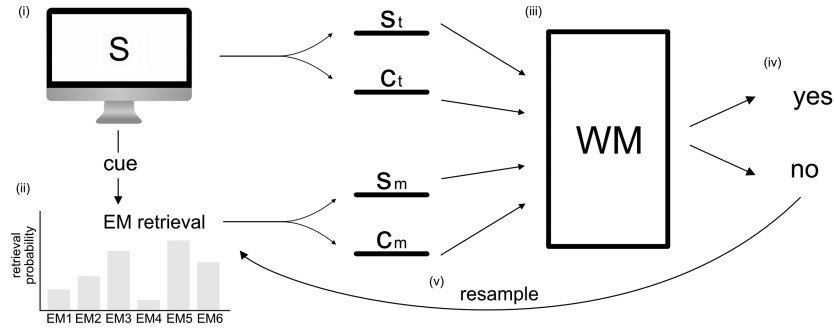
The network described above was trained in the simplest possible way in order to perform the *N*-back task. In this task, a participant is presented with a sequence of stimuli, one at a time, and must judge whether each stimulus matches the one presented *n* stimuli ago in the sequence. For example, in the two-back version, for the sequence A-A-B-C-B-A the correct response is “no” for the first four stimuli and the last, while it is “yes” for the fifth stimulus (the repeat of the

Figure 1
Lower Discriminability Between Target Item and Lure for Three-Back Compared to Two-Back



Note. Left and middle panels: Histograms showing distance between current item and target item (green) or neighboring lure (blue) for two-back (left) and three-back (middle) targets. Note greater overlap between targets and lures for three-back compared to two-back task. Right panel: ROC curves for distinguishing target from lures in three-back (yellow) and two-back (red). ROC = Receiver Operator Characteristic. See the online article for the color version of this figure.

Figure 2
Schematic Showing the Organization and Sequence of Processing Steps in the Model of the N -Back Task



Note. Model. (i) The stimulus is presented; (ii) the stimulus serves to cue memory traces; (iii) the stimulus and memory along with their respective context values are passed through the WM neural network to (iv) produce a response. If no match is found, (v) the model resamples from EM and continues. WM = working memory; EM = episodic memory.

“B” that appeared two stimulus after the first). While a naive participant might never have actually performed this particular task, people nevertheless come to the task knowing both how to match two representations based on a specified stimulus feature and how to discern relative serial positions. To capture this prior knowledge that is required to perform the task, we trained the neural network to determine whether: (a) the stimulus component of the trace retrieved from EM (s_m) was the same as the stimulus component of the current external input (s_t); and (b) the context component of the trace (c_m) was n (2 or 3) steps earlier than the context component of the current external input (c_t). That is, each training epoch consisted of a judgment about whether the stimulus and context components of a trace retrieved from EM was an n -back match to the stimulus and context components of the current input. This gave four combinations of external (stimulus plus temporal context) and memory trace inputs to the network: *match* (matching stimulus, n -back context), *nonmatch* (nonmatching stimulus, not- n -back context), *stimulus-only match* (matching stimulus, not- n -back context), and *context-only match* (nonmatching stimulus, n -back context). Note that, while training the network, we did not explicitly model the EM retrieval process, nor the mechanisms responsible for coordinating EM retrieval with processing by the feedforward network.⁵ These generally involve the inclusion of recurrent networks that would potentially confound the interpretation of results of interest in our study. Thus, both for simplicity of implementation and clarity of interpretation, we chose not to include such mechanisms while training the present model (though we did include an EM retrieval mechanism that was coordinated with processing by the feedforward network when the model was tested, as described in Section Similarity-Based Retrieval, Match, and Response Processes). In the General Discussion, we return to this issue, which we consider an important direction for future research.

The network was first pretrained to process the four input combinations described above, and was then combined with the EM module to perform the N -back task for testing (as described below). Since training involved learning to make relative serial position determinations, and this in turn relied on the nature of the temporal context encodings (see Section Formulation of Context

Representations), we trained the model on stimuli presented at various serial positions in a sequence of length 48 (the number of stimuli per block in the M. J. Kane et al., 2007 empirical study to which we compared model performance). We did so by simulating a sequence of 48 steps of temporal evolution (“drift”) in the context representation (see Section Formulation of Context Representations), and then setting the context component (c_t) of the current input to a randomly selected step in that sequence. The stimulus component of the input was then selected from the set of possible one-hot stimulus vectors. The outcome of this process was a sequence of stimuli that were accompanied by a drifting context representation. Finally, the task input was determined by alternating the task specification (two-back or three-back) and randomly selecting from one of the four possible conditions, which was then used to assign the stimulus (s_m) and context (c_m) components of the trace retrieved from EM, as follows:

1. *match trial*: The same vector used for s_t was assigned to s_m ($s_t = s_m$), and c_m was the context from n steps before the current context ($c_m = c_t(t - n)$);
2. *nonmatch trial*: s_m was a randomly chosen one-hot vector different from the current stimulus ($s_t \neq s_m$), and c_m was randomly drawn from the context values from less than $2n$ steps ago excluding n ($c_m = c(t - k)$; k in $[t - (2n - 1), \dots, t - n - 1, t - n + 1, \dots, t - 1]$);
3. *stimulus-only match trial*: s_m was assigned as in a match trial ($s_t = s_m$), while c_m was assigned as in a “nonmatch” trial ($c_m = c(t - k)$; k in $[t - (2n - 1), \dots, t - n - 1, t - n + 1, \dots, t - 1]$);
4. *context-only match trial*: The s_m was assigned as in a nonmatch trial ($s_t \neq s_m$) while c_m was assigned as in a match trial ($c_m = c(t - n)$).

⁵ Both the mechanisms responsible for EM retrieval, and for coordinating interactions between EM and WM, are interesting and important subjects of ongoing investigation (Graves et al., 2014; Norman & O’Reilly, 2003; Pritzel et al., 2017; Ritter et al., 2018; Wayne et al., 2018; Webb et al., 2021).

On each training trial, a single forward processing and backward weight-adjusting pass of the backpropagation algorithm (Rumelhart et al., 1986) was executed. The training labels were “Yes” for match trials and “No” for all other trial types. 40% of the training trials were match trials and the other 60% of training trials were evenly divided among the other trial types. Training trials were alternated between the two-back and the three-back conditions of the task. The model was trained on 400,000 trials per task (total of 800,000 epochs). During model testing, learning was disabled, so that no additional weight changes were possible.

Similarity-Based Retrieval, Match, and Response Processes

To simulate performance of the *N*-back task, we incorporated the EM mechanism described in Section EM Component, that stored traces of the stimulus and associated context (one for each item presented in a sequence of trials of the task) with the feedforward model trained on the discrimination and match process as described just above. This further required specification of how, on each trial, items were retrieved from EM and provided as input to the WM network (see note in Section Feedforward Neural Network Training). Inspired by previous work that has combined neural networks with EM storage, we implemented EM retrieval using a similarity-based search process (Graves et al., 2014; Lu et al., 2022; Ritter et al., 2018; Wayne et al., 2018; Webb et al., 2021). In the present model, the current stimulus and accompanying context representation were used as retrieval cues. On each trial, the model computed the similarity of the currently presented stimulus s_t and corresponding context c_t , with each stimulus (s_m) and context (c_m) pair stored in EM. An overall memory similarity was calculated as a weighted sum of these terms:

$$\text{sim} = w_1 \cos(c_t, c_m) + w_2 \cos(s_t, s_m). \quad (3)$$

Note that the similarity between the current input and each memory trace was computed separately for their stimulus and context components, and weighted according to w_1 , w_2 before combining them into a single similarity score for each trace. A single relative weighting of stimulus-based similarity (w_1) and context-based similarity (w_2), which was held constant across all comparisons, was optimized to best fit behavioral data (see Section Results below). The values we arrived at were $w_1 = 0.05$ and $w_2 = 0.95$, indicating that the model was weighting context information more heavily than stimulus information when computing the similarity score.⁶ The retrieval process then proceeded as follows:

1. a softmax was computed over the similarities between the current input and all traces in EM, to get the probability of retrieval of each memory;
2. the softmax values were used to probabilistically select a memory for retrieval (without replacement, as in Polyn et al., 2009; see step 5 below) which was passed to the h1 hidden layer of the WM network, along with the current stimulus and context;
3. if the WM network detected a match, the retrieval process terminated and the model responded “match”;
4. if no match was detected in step 3, with probability *hrate*, the retrieval process was terminated and the model responded “no match” (*hrate* = 0.04 across all tasks and conditions and was determined along with w_1 and w_2 by a fit to empirical data; see Section Results);
5. if no match was detected in step 3, and step 4 did not probabilistically trigger a “no match,” steps 2–4 were repeated until the memory search terminated or until there were no more memories in EM to sample in which case the model also responded with “no match.”

Thus, in summary, the EM retrieval process amounted to sampling memory traces from EM in proportion to the similarity of the currently presented stimulus and context to the stimulus and context of each EM trace (weighted by w_1 and w_2 , respectively) and continued on a given trial either until the retrieved trace was judged to be an *N*-back match to the current stimulus or it was terminated probabilistically (according to the hazard rate *hrate*).

N-Back Simulation and Analysis

We simulated the experiments conducted by M. J. Kane et al. (2007), which compared three-back versus two-back in eight blocks of 48 trials each, using eight phonologically distinct letters. The analysis involved distinguishing eight different conditions, defined by the crossing of three factors: set size (two- vs. three-back instruction), match versus nonmatch (does the current stimulus match the *n*-back stimulus), and the presence or absence of a lure (does the current stimulus also match the $n - 1$ back stimulus). Crossing the match and lure factors yielded four sequence types (closely related but not identical to the training conditions described above); for example, in the three-back condition, these were: (a) match sequences (A B C A); (b) nonmatch sequences (B C D A); (c) match-lure sequences (A A B A); and (d) nonmatch-lure sequences (B A C A).⁷ Thus, sampling these four sequence types for the two set sizes (two-back and three-back) yielded eight conditions, that we used in our simulations. Following the M. J. Kane et al. (2007) study, simulated trials were constructed in blocks of 48; each trial involved presenting a stimulus drawn from one of the eight possible conditions at a particular point in the block, and the model had to judge whether that stimulus was an *n*-back match or not. To simulate the t^{th} trial in a block, the current (t^{th}) stimulus was randomly drawn from the set of possible stimuli (e.g., it was set to A). Then, depending on the experimental condition being simulated, the preceding *n* stimuli were selected to instantiate that condition, by loading them into EM. To simulate the key assumption that EM traces are durable, EM was also loaded with randomly selected stimuli for all of the trials in that block preceding the one *n*-back. For example, in the 19th trial of a three-back block, if the current stimulus was A in a match sequence, then the 16th, 17th, and 18th stimuli would be chosen as A, B, and C, so that three-back stimulus (A) matched but the two-back (B) did not. Then, the stimuli for the preceding trials in the block (i.e., the 1st through 15th trials) were randomly chosen from the set of all possible stimuli,

⁶ This difference in weighting could potentially reflect the fact that differences in context vectors from trial to trial were smaller in magnitude than differences in stimulus vectors.

⁷ In M. J. Kane et al. (2007), these sequence types are referred to as *control target*, *control foil*, *lure target*, and *lure foil*, respectively.

such that on the 19th trial, the model has 18 EM traces available for retrieval, some of which could match the current stimulus. Finally, we generated a drifting sequence of t context vectors (one per trial), in which the t^{th} context vector in the sequence was designated as the current context, and we stored episodic memories for the $t - 1$ trials preceding the current trial each paired with the corresponding context vector (e.g., the EM trace corresponding to the 15th trial would contain the 15th stimulus and the 15th context vector). Once the current stimulus and context were fixed, and the contents of EM were defined, the model produced a response as described in Section Similarity-Based Retrieval, Match, and Response Processes.

Results

We compared the results of the simulations described above with those reported by M. J. Kane et al. (2007), using the same signal-processing metrics to analyze performance that they used to analyze their empirical data (hits, correct rejections, d' sensitivity, and C bias). These were calculated separately for each of the eight conditions (again, two-back and three-back set sizes crossed with the four sequence types). Figure 3 shows that the pattern of results from the simulations closely matched those of the empirical study.

Set-Size effect

In the N -back task, the set-size effect manifests as lower sensitivity in the three-back task compared to the two-back task. This effect was robustly present both in humans and the model. The human data show a strong main effect of lower hit-rate in the three-back compared to the two-back condition. This was also observed in the model.⁸

Lure Effects

In the N -back task modeled here, the term “lure” is used to refer to a sequence of stimuli in which a stimulus in the $n - 1$ position matches the current stimulus. This could occur either in match sequences (which also contain an n -back match) or in nonmatch sequences (which do not contain an n -back match). The lure effect manifests as lower sensitivity in conditions with (vs. without) lures, as the $n - 1$ back item is likely to be confused with the n -back item. We found that this effect of reduced sensitivity was robustly present both in humans and in the model. The lure effect was primarily driven by higher false alarm rates to nonmatch-lure sequences (e.g., for three-back, B A C A) than to nonmatch sequences (B C D A). False alarms to nonmatch-lure sequences occur because noise accumulation in context drift can lead to confusion between adjacent serial positions (see Figure 1); for example, in the sequence B A C A, when the A that occurred in the $n - 1$ position is retrieved, the retrieved context is sometimes misattributed to the n -back position, leading to a spurious “match” response. Interestingly, the effect of the lure manipulation on hits was different in the model as compared to humans. The model showed more hits on lure trials than nonmatch trials for the same reason it showed more false alarms on lure trials—it would sometimes give a spurious “match” response after retrieving a lure. Humans showed the opposite pattern of results in the three-back condition (more hits on control trials than lure trials), an observation that will require additional modeling and/or empirical work to understand.

General Discussion

In this article, we presented a model of the N -back task that simulated human performance on this task, exhibiting empirically observed set-size (as well as lure) effects that, in the model, arose strictly from PI due to contextual drift and degradation of temporal distinctiveness in the retrieval of information from EM. Our findings lend support to the view that EM may be engaged by—and contribute to set-size effects in—tasks widely used to index WM function, as discussed further below. The demonstration of these effects is particularly relevant in the context of the N -back task, given both its wide use as an index of WM function (M. J. Kane et al., 2007; Oberauer et al., 2018), and because our findings suggest that the strong set-size effects observed in this task need not be attributed to constraints in either the storage *or* processing capacity of WM (e.g., Rac-Lubashevsky & Kessler, 2016). As reviewed above, our model showed robust set-size effects despite having no capacity whatsoever for the retention of information in WM (all information about previous stimuli was stored in EM), and despite having sufficient WM processing capacity to handle the demands of the task (WM processing simply involved comparing the information retrieved from EM with the information currently in WM and generating a response). In the remainder of this discussion, we consider the relationship of our model to other models of the N -back task, as well as current theories of EM, WM, and their interactions.

Relationship to Existing N -Back Models

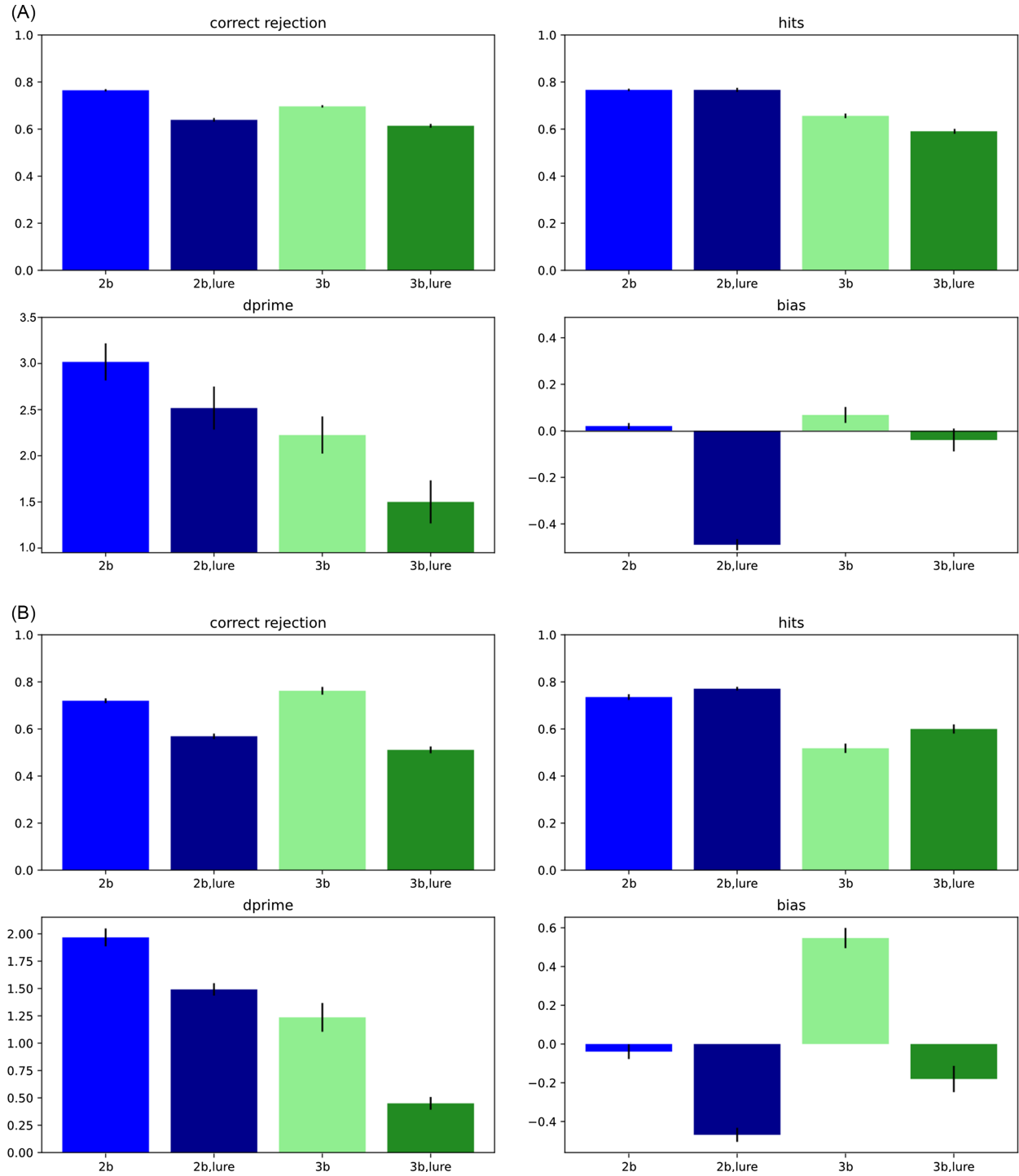
To date, there have been relatively few published mechanistic models of the N -back task. Here, we compare our model to two of these that are representative of how previous work has treated the role of WM in performance on the N -back task. One of these models, reported by Chatham et al. (2011), used a neural network to implement a biologically plausible mechanism for the active maintenance and processing of information in WM, based on a previous model of prefrontal cortex and basal ganglia function (Frank et al., 2001). Chatham et al. (2011) showed that this model could replicate set-size and lure effects in the N -back task. Our findings complement these results, showing that a neural network model that uses WM to process information (i.e., evaluate for a match and elicit a response), but that relies exclusively on EM rather than active maintenance in WM for retaining information across trials, can produce comparable results.

Another model, reported by Juvina and Taatgen (2007), explores how two different strategies can be used to perform the N -back task. One of these relies on the active maintenance of information in WM, paralleling at an abstract level the Chatham et al. (2011) model. The other strategy relies on a form of storage similar in important respects to more recently proposed alternative forms of storage in WM (Oberauer, 2019; Stokes, 2015; discussed further below, in Section Relationship to “Dual System” Models of Immediate Memory). Juvina and Taatgen refer to these strategies as “high control” and “low control,” respectively, and implemented them in two distinct models using the ACT-R architecture (Anderson et al., 1997). In their high-control model, a window of size n stimuli was actively maintained by a rehearsal process, and the ordinal position of

⁸ We report findings here for the two set-sizes studied in M. J. Kane et al. (2007). Findings for a wider range of set-sizes are reported in the Appendix.

Figure 3

Comparison of Model Performance With Empirical Data From M. J. Kane et al. (2007)



Note. (A) Human and (B) model results, showing hit rate (correctly replying “match” on match and match-lure trials), correct rejection rate (correctly replying “no match” on nonmatch and nonmatch-lure trials), sensitivity, and bias, as a function of set size (two-back vs. three-back) and whether or not a lure was present at the $n - 1$ -back position (see text for explanation of sequence types). Error bars indicate the standard error of the mean. (A) Human data reproduced from “Working memory, attention control, and the n -back task: A question of construct validity,” by M. J. Kane, A. R. A. Conway, T. K. Miura, and G. J. H. Colflesh, 2007, *Journal of Experimental Psychology: Learning, Memory, and Cognition*, 33(3), pp. 615–622 (<https://doi.org/10.1037/0278-7393.33.3.615>). Copyright 2007 by the American Psychological Association. (B) Data from model simulations, averaging across 10 runs of the model, corresponding to $N = 10$ participants. See the online article for the color version of this figure.

each item was encoded by the item's position in this actively maintained window. This can be thought of as implementing a WM-based mechanism for retaining information in an actively maintained state. In contrast, in their low-control model, each item was stored along with a time-tag that specified the moment of encoding, following the time-tag account of Yntema and Trask (1963). This implements a form of temporal context dependence similar to the one implemented in our model: Time-tags were encoded in memory and then retrieved (in response to repeated stimuli) and used to make serial position judgments.

Critically, however, an important difference between the storage mechanism in Juvina and Taatgen's low-control model and the one in the model presented here is that theirs involved memory decay that was used to explain the set-size effect (i.e., memories decayed with time, making three-back targets less likely to be retrieved than two-back targets). By contrast, the model presented here relied on noisy contextual drift and temporal distinctiveness to explain set-size effects, without positing any dedicated decay mechanisms. This reliance on temporal distinctiveness (and not decay) to explain set-size effects aligns with classic work suggesting that decay, on its own, is not a major source of forgetting in EM (e.g., A. Baddeley & Hitch, 1977). As discussed in the next section, our model implements time-tags in a form that is also closely related to other models of temporal context-based memory (Howard & Kahana, 2002; Polyn et al., 2009), while using a formally specified while neurally plausible representational coding scheme (i.e., as value-constrained drifting context vectors), and shows how a simple neural network model can learn to use such context vectors to perform the temporal discrimination and matching processes required by the task. Thus, while our model aligns with the theoretical proposition advanced in Juvina and Taatgen (2007) and by others (e.g., Oberauer et al., 2012)—that set-size effects may not necessarily reflect reliance on active maintenance in WM for retention—it relies on a different mechanism for explaining degradation in performance with set size, which is more closely aligned with contemporary work on storage and retrieval from EM (discussed below) than other forms of WM, while also offering a neurally plausible implementation of the mechanisms involved. It also relates closely to the growing body of work on neural network models that make use of interactions between EM and WM for higher cognitive functions, such as planning and generalization, to which we return in Section Other Interactions between EM and WM.

Relationship to Existing Context and Temporal Distinctiveness Models

Our model of storage and retrieval from EM aligns closely with existing context-based memory models, such as the TCM (Howard & Kahana, 2002) and the context maintenance and retrieval model (Lohnas et al., 2015; Polyn et al., 2009). These models explain a wide range of findings from serial recall and free recall paradigms in terms of a gradually drifting temporal context representation. For example, recency effects in free recall (i.e., better recall of more recent items) can be explained as a consequence of a greater match between the current context and the context associated with recent (vs. more temporally distant) memories (Howard & Kahana, 2002). Here, we focus on a different consequence of the similarity

properties of context representations as a function of time: If drifting context representations carry serial position information that is reinstated by retrieved EM traces, this serial position information can be used for carrying out task-relevant computations in WM—in this case, identifying whether an item was presented two-back or three-back. Extending the work of Brown et al. (2007) and others, we show how confusability of retrieved context representations can lead to memory errors in the *N*-back task.

Relationship to “Dual System” Models of Immediate Memory

The model we present here is certainly not the first to posit that more than one system may contribute to immediate memory. Dating back to at least James (2007), it has been acknowledged that such memory is best explained as multiple interacting systems. Here, we compare and contrast our model with two notable instances of such models in the literature: the dual-system framework of Unsworth and Engle (2007) and the “serial-order-in-a-box”—complex span (SOB-CS) model of Oberauer et al. (2012).

Following from terminology introduced by William James, Unsworth and Engle (2007) describe a model composed of two interacting memory systems, primary memory and secondary memory. Similar to traditional concepts of WM, primary memory is described as a dynamic and attention-driven component that manipulates a small number of items (2–7). This capacity constraint is then used to explain limitations in performance such as the set-size effect. Unsworth and Engle (2007) also describe a secondary memory component that, like our EM module, has no capacity constraints and from which items must be retrieved by a probabilistic cue-dependent retrieval process. The difference between this secondary memory mechanism and the model of EM presented here relates to the process responsible for retrieval. Specifically, retrieval from secondary memory is achieved through an active search process, that strategically formulates cues to delineate a search set from which a memory is sampled. In contrast, in our model, retrieval from EM is automatically triggered on every trial, by the similarity between the item and context currently active in WM and the item and context stored in EM traces. Thus, while the framework in which our model was constructed allows for the possibility that additional strategic processes may be involved in actively searching for and selecting cues to constrain what information is retrieved from EM (e.g., processes that might come into play at the very beginning of the experiment, to determine that the current stimulus and context are all that are needed to cue retrieval from EM), our model suggests that such strategic mechanisms are not needed—at least not on a trial-by-trial basis—to account for the set-size and lure effects that are observed empirically.

Along these lines, an additional parallel between our work and that of Unsworth and Engle (2007) relates to the use of a context representation to guide the retrieval process. Although their theory does not formally specify the coding scheme of context representations, the authors make the intriguing suggestion that context could be hierarchically specified. For example, when studying a list of items, each item would be associated with a global context, a list context, and an item-level context. Here, we formally represent the item-level context as an automatic temporal drift process, in line with the existing formalisms from the EM literature, and in particular, the temporal context memory model of Howard and

Kahana (2002). An interesting future direction might be to explore what other phenomena could be modeled if we allowed context representations to be hierarchically structured, and/or have different content and/or dynamics under different circumstances that might even be strategically controlled. For example, to model the effect of list-level context, we could either augment the context vector to have different entries that drift at different rates and/or allow for the context to take a single large step at the end of a list. In both cases, this should have the effect of making items from different lists more distinguishable than ones within lists.

In another dual-system model, Oberauer et al. (2012) built on the “context-serial-order-in-a-box” (C-SOB) model (Farrell, 2006; Lewandowsky & Farrell, 2008) to propose the SOB-CS model for the complex span task. On each trial of this task, participants are given a list of items to remember followed by a distractor task (e.g., doing algebra, or making a lexical decision) after which they must recall the list. The task is designed to tax the participant’s ability to retain information while performing manipulations in WM. Like the Unsworth and Engle (2007) model, the SOB-CS model is also composed of two components. Similar to primary memory, SOB-CS has a mechanism for the focus of attention that contains a limited amount of activated information available for processing (corresponding to WM). Similar to secondary memory, memories that are in the focus of attention are stored along with their context in a more durable component from which items can later be retrieved (corresponding to EM).

Our model is similar to SOB-CS in that it explains memory failures in terms of interference (as opposed to decay) mechanisms. However, it differs with respect to how this arises. In SOB-CS, items are associated with their respective context by Hebbian learning in a weight matrix, which is used to store them in secondary memory. Importantly, this applies both to memory list items and items in the distractor task. Because memories are stored in the same weight matrix that has a fixed dimensionality (i.e., constrained capacity), they can interfere with and eventually start overwriting each other. Oberauer et al. (2012) show that, as memories accumulate in the memory matrix, such interference can explain a series of memory effects including the set-size effect and serial position effects in list recall. The effects in our model have some similarities to those exhibited by SOB-CS, and at some level of abstraction, these models may be formally related to one another. However, the mechanisms underlying these effects differ: in our model memories in EM accumulate independently without directly interfering with one another, and interference is driven entirely by the effects of similarity structure on retrieval—in particular, the similarity of items with respect to their temporal context representations.

Another difference between our model and SOB-CS is the forgetting mechanism. To prevent interference from completely bogging down memory, Oberauer et al. (2012) posit an active retrieval mechanism implemented by Hebbian antilearning that clears the irrelevant items from the memory matrix during free time. In contrast, in our model, an effect comparable to “clearing” is accomplished without any dedicated machinery for this; rather, once again it emerges directly from an interaction between the two fundamental mechanisms in the model: encoding of slowly drifting temporal context representations and similarity-based retrieval. As the current temporal context representation drifts further away from the context representations associated with the previous items, those

previous items become less accessible for retrieval and thus less interfering.

Perhaps the most important, broader observation to be made about efforts to model immediate memory is that the gap between models of WM and EM has narrowed considerably: Mechanisms that previously had been part only of EM models (e.g., item-context binding) are now frequently included in models of WM, such as the Oberauer et al. (2012) model discussed above; at the same time, effects historically associated with WM (such as set-size effects) are increasingly being considered with respect to EM. In this context, we emphasize that the goal of the work reported here was not to promote the exclusive, or even primary role of EM in contributing to retention of information in WM tasks (in general) or the *N*-back task (in particular). Rather, it was to help refine the functional definition of and distinction between these memory mechanisms, and to demonstrate in as clear a way as possible that three fundamental properties associated with EM (similarity-based retrieval of durable memory traces that bind items to a drifting temporal context) are *sufficient* to account for set-size and lure effects in a task widely used to probe WM function (i.e., the *N*-back task), without asserting either their necessity or primacy.

Other Interactions Between EM and WM

In this theoretical note, for the reasons just mentioned, we focused on one form of complementary interaction between EM and WM, in which EM serves as the mechanism for retention, and WM for computation. In reality, it is almost certain that performance in any given task relies on the participation of both, in ways that vary by task condition. Indeed, a growing number of models suggest interactions between EM and WM may be a central, not just an incidental feature of cognitive function (A. Baddeley, 2000; Beukers et al., 2021; Cowan, 1999, 2019; Dulberg et al., 2021; Foster et al., 2019; Oberauer, 2009; Rose, 2020; Webb et al., 2021). For example, Cohen and O’Reilly (1996) proposed that an interaction between these systems may provide an account of prospective memory—that is, remembering to perform a task in the future (Einstein & McDaniel, 2005)—in which EM serves to store an association between a representation of the desired task and the circumstances in which it is to be performed, so that the task representation can be retrieved when those circumstances occur. This provides a mechanistic undergirding of two-process theories of prospective memory (Einstein & McDaniel, 2005; McDaniel & Einstein, 2000, 2007), which have received empirical support from both behavioral and neural data (e.g., Beck et al., 2014; Einstein et al., 2005; Lewis-Peacock et al., 2016; McDaniel et al., 2013), and have recently been subjected to normative analysis (Momennejad et al., 2021). Furthermore, recent work in machine learning has suggested that interactions between EM and recurrent neural network mechanisms that support gradual learning and WM (such as long short-term memory mechanisms, Hochreiter & Schmidhuber, 1997) may be critical for other forms of higher cognitive function, such as the learning of abstract rules and their use in reasoning and problem solving (Altabaa et al., 2023; Graves et al., 2014; Mondal et al., 2023; Vaishnav & Serre, 2022; Webb et al., 2021). In this light, the work presented in this article contributes to research addressing the computational relationship between EM and WM, a direction

that promises to be an increasingly important and productive one for understanding higher cognitive function.

Concluding Remarks

Advancing our understanding of human cognitive function requires understanding how different subsystems interact, including the different memory systems. In this theoretical note, we focused on one potential interaction, between WM and EM. Our model provides a neural network implementation of how context representations may be encoded in and used for retrieval from EM, and how this may be used for WM computations involving serial position information. We describe a computational account of these interactions, showing that they can produce set-size and lure effects in the *N*-back task similar to those observed in human performance. The robust nature of these effects in the *N*-back task has likely contributed to its widespread use as an index of WM function, under the assumption that they reflect limits to the storage and/or processing capacity commonly ascribed to WM. The work presented here joins other lines of work that suggest caution is warranted in this inference, reinforcing the idea that well-established properties of EM—similarity-based retrieval of temporal context representations—are sufficient to elicit such effects. Future work should focus on the development of more detailed experimental and analysis methods that can be used to disambiguate the contributions of WM and EM to task performance, as well as their interaction in the service of memory and their role in higher cognitive function. We also hope that the formulation of our model within the context of a neural network architecture will facilitate contact with work both in neuroscience and machine learning that explores the mechanisms of interaction between EM and WM.

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(Appendix follows)

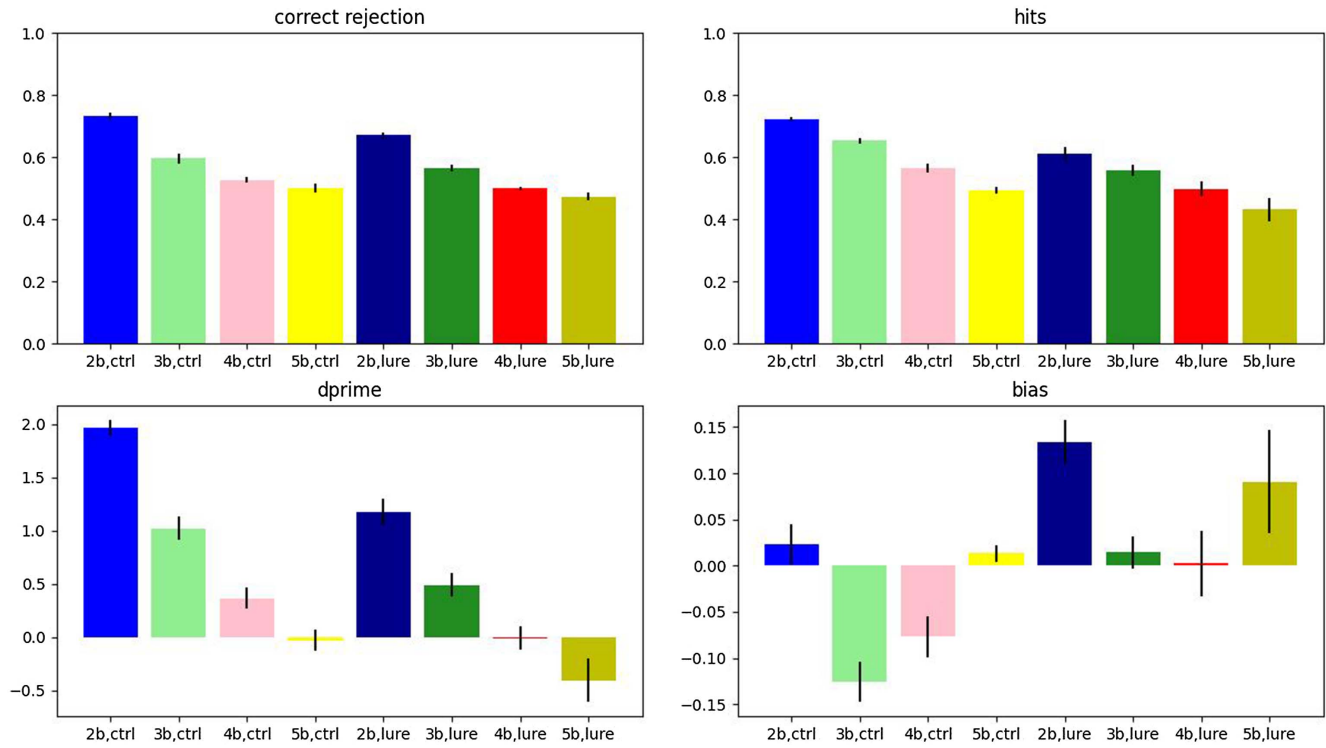
Appendix

Extended Version of the *N*-Back Model

Figure A1 shows an extended version of the model results from Figure 3, with *N*-back values extending from 2 to 5. Methods for these simulations were the same as for the simulations in the main text; the only difference is that four-back and five-back conditions were included. Sensitivity (indexed using *d'*) drops to zero in the

five-back control condition and the four-back lure condition. This finding could naively be interpreted as reflecting a strict limit in storage and/or processing capacity, but—in the model—it is driven by the decreasing discriminability of retrieved contexts for adjacent serial positions as *N*-back increases.

Figure A1
Performance of the Extended Model on Two- to Five-Back Conditions



Note. Extended version of model results from Figure 3 showing hit rate (correctly replying “match” on match and match-lure trials), correct rejection rate (correctly replying “no match” on nonmatch and nonmatch-lure trials), sensitivity, and bias, as a function of set size (two-back all the way through five-back) and whether or not a lure was present at the *n* – 1-back position. Ctrl refers to the control condition. See the online article for the color version of this figure.

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